# Lecture 6: Euler Approximation

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#### Abstract

Backward and forward representation, strong and weak convergence of Euler approximation.

## 1 Euler Method: Order of Convergence

SDE:

$$dX_t = a(t, X_t)dt + b(t, X_t)dW_t, \ t \in (0, T],$$
(1.1)

with initial value  $X_0$  at t = 0. Discrete times  $0 = t_0 < t_1 < t_2 < \cdots < t_n < \cdots < t_N = T$ . Denote  $\Delta_n = t_{n+1} - t_n$ ,  $\delta = \max \Delta_n$ . Euler approximation:

$$Y_{n+1} = Y_n + a(t_n, Y_n)\Delta_n + b(t_n, Y_n)(W_{t_{n+1}} - W_{t_n}),$$
(1.2)

with  $Y_0 = X_0$ .

 $Y_n$  is  $A_n$  measurable.

Connecting the adjacent discrete values  $Y_n$  by straight lines form a continuous function Y(t). Pathwise measure of approximation is:

$$\epsilon = E(|X(T) - Y(T)|), \tag{1.3}$$

reduces to deterministic absolute error at t = T if noise is absent. In actual computation, suppose we have N solutions  $Y_k(T)$  from N realizations of BM, then  $\epsilon$  is approximated by:

$$\tilde{\epsilon} = \frac{1}{N} \sum_{k=1}^{N} |X_k(T) - Y_k(T)|.$$
(1.4)

It is an amusing fact that  $\epsilon \sim O(\delta^{1/2})$  in the stochastic case while  $\epsilon \sim O(\delta)$  in the deterministic case. This is analyzed below.

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### 1.1 Strong Convergence/Consistency

Strong Convergence if:

$$\lim_{\delta \to 0} E(|X(T) - Y_{\delta}(T)|) = 0.$$
(1.5)

Strong Convergence with order  $\gamma > 0$ :

$$E(|X(T) - Y_{\delta}(T)|) \le C\delta^{\gamma}, \tag{1.6}$$

for any  $\delta \in [0, \delta_0], \delta_0 > 0$ . Strong Consistency of Discrete Approximation:

$$E\left(|E(\frac{Y_{n+1}^{\delta} - Y_n^{\delta}}{\Delta_n} | A_{t_n}) - a(t_n, Y_n^{\delta})|^2\right) \le c(\delta) \to 0,$$
(1.7)

and:

$$E\left[\frac{1}{\Delta_n}|Y_{n+1}^{\delta} - Y_n^{\delta} - E(Y_{n+1}^{\delta} - Y_n^{\delta}|A_{t_n}) - b(t_n, Y_n^{\delta})\Delta W_n|^2\right]$$
  
$$\leq c(\delta) \to 0.$$
(1.8)

for all fixed  $Y_n^{\delta} = y, n = 0, 1, 2, \cdots$ . For Euler, strong consistency holds with  $c(\delta) \equiv 0$ .

### 1.2 Convergence

Consider the autonomous SDE:

$$dX_t = a(X_t)dt + b(X_t)dW_t, (1.9)$$

**Theorem 1.1** A strongly consistent equidistant time discrete approximation  $Y_n^{\delta}$  of (1.9) with  $Y^{\delta}(0) = X_0$  converges strongly to X. In particular, Euler method converges strongly with order 1/2.

Sketch of Proof:

$$Z(t) = \sup_{s \in [0,t]} E(|Y_{n_s}^{\delta} - X(s)|^2),$$

$$n_s = \max\{n : t_n \le s\}.$$

$$Z(t) = \sup_{s \in [0,t]} E[|\sum_{n=0}^{n_s-1} (Y_{n+1}^{\delta} - Y_n^{\delta}) - \int_0^s a(X_r)ds - \int_0^s b(X_r)dW_r|^2]$$

$$\leq C_{1} \sup_{s \in [0,t]} \left\{ E[|\sum_{n=0}^{n_{s}-1} (E(Y_{n+1}^{\delta} - Y_{n}^{\delta}|A_{t_{n}}) - a(Y_{n}^{\delta})\Delta_{n})|^{2}] + E[|\sum_{n=0}^{n_{s}-1} (Y_{n+1}^{\delta} - Y_{n}^{\delta} - E(Y_{n+1}^{\delta} - Y_{n}^{\delta}|A_{t_{n}}) - b(Y_{n}^{\delta})\Delta W_{n})|^{2}] + E[|\int_{0}^{t_{n_{s}}} a(Y_{n_{r}}^{\delta}) - a(X_{r}) dr|^{2}] + E[|\int_{0}^{t_{n_{s}}} b(Y_{n_{r}}^{\delta}) - b(X_{r}) dW_{r}|^{2}] + E[|\int_{t_{n_{s}}}^{s} a(X_{s})ds|^{2}] + E[|\int_{t_{n_{s}}}^{s} b(X_{s})dW_{s}|^{2}] \right\}$$
(1.10)

by strong consistency and Lipschitz condition:

$$Z(t) \le C_2 \int_0^t Z(s) ds + C_3(\delta + c(\delta)),$$
(1.11)

the last term of (1.10) contributes  $O(\delta)$ . Gronwall inequality:

$$Z(t) \le C_4(\delta + c(\delta)), \tag{1.12}$$

or:

$$E(|Y^{\delta}(T) - X(T)|) \le C_5 \sqrt{\delta + c(\delta)}, \qquad (1.13)$$

strong convergence. For Euler,  $c(\delta) = 0$ ,  $\gamma = 1/2$ .

## 2 Backward and Forward Representations

Let X(t) be a diffusion process (solution of SDE) with drift a(t, x), diffusion b(t, x):

 $dX_t = adt + bdW_t,$ 

consider the conditional expectation (s < t):

$$E(f(X_t)|X_s = x) = \int f(y) \, p(s, x; t, y) \, dy, \qquad (2.14)$$

where p(s, x; t, y) is the transition probability density function from (s, x) to (t, y). As a function of (s, x), p satisfies the *backward equation*:

$$p_s + \frac{1}{2}b^2(s,x)p_{xx} + a(s,x)p_x = 0.$$
(2.15)

Hence  $u(s, x) = E(f(X_t)|X_s = x)$  solves (2.15) with final condition u(t, x) = f(x). For the forward representation, consider the Autonomous case, a = a(x), b = b(x). Then p(s, t; x, y) = p(t - s; x, y),  $p_s = -p_t$ ,

$$p_t = \frac{1}{2}b^2(x)p_{xx} + a(x)p_x, \ t > s,$$
(2.16)

 $p(t; x, y) \rightarrow \delta(y - x)$ , as  $t \rightarrow 0+$ . The transition probability density becomes fundamental solution of parabolic equation (2.16). As a function of (t, x),

$$v(t,x) = E(f(X_t)|X_s = x) = \int f(y) \, p(t-s;x,y) \, dy, \qquad (2.17)$$

solves:

$$v_t = \frac{1}{2}b^2(x)v_{xx} + a(x)v_x, \qquad (2.18)$$

with initial data v(s, x) = f(x).

**Feynman-Kac Formula** Eq. (2.17) is a probabilistic representation formula of PDE (2.18). It can be generalized to include a lower order (potential, V) term as in Eqn:

$$w_t = \frac{1}{2}b^2(x)w_{xx} + a(x)w_x + V(x)w, \ t > 0,$$
(2.19)

initial data: w(0, x) = f(x). Then,

$$w(t,x) = E\left[\exp\{\int_{0}^{t} V(X_{\tau}) \, d\tau\}f(X_{t})\right],$$
(2.20)

Rmk: If the diffusion  $b(x) \equiv 0$ , F-K formula reduces to a solution formula of first order hyperbolic eqn by the method of characteristics.

**To derive (2.20)**, let:

$$T_t f = E\left[\exp\{\int_0^t V(X_\tau) \, d\tau\}f(X_t)\right],\,$$

a linear bounded (non-negative) operator on the space of bounded continuous functions. Note:

$$\exp\{\int_0^t V(X_s)ds\} = 1 + \int_0^t V(X_s)ds + o(t),$$

as  $t \to 0+$ . We have for any f(x) in the domain of  $T_t$ :

$$\frac{T_t f(x) - f(x)}{t} = \frac{1}{t} \left( E[f(X_t) e^{\int_0^t V(X_s) ds}] - f(x) \right) \\
= \frac{1}{t} (E[f(X_t)] - f(x)) + \frac{1}{t} E[f(X_t) \int_0^t V(X_s) ds] \\
\rightarrow (b^2(x) f_{xx}/2 + a(x) f_x) + V(x) f.$$
(2.21)

We have used (2.16) for the limit of first term.

To generalize F-K to nonautonomous case, we should notice trick in (2.16) no longer works. Treat t as a parameter,

$$dX_{s}^{t,x} = a(t_{s}^{t,x}, X_{s}^{t,x})ds + b(t_{s}^{t,x}, X_{s}^{t,x})dW_{s}, dt_{s}^{t,x} = -ds,$$
(2.22)

 $X_0^{t,x} = x, t_0^{t,x} = t$ , symmetrically extending  $a, b: a(-\tau, x) = a(\tau, x)$  etc. View (2.22) as a diffusion process on  $(t, x) \in \mathbb{R}^2$  with time s. Eqs (2.22) are autonomous, and define a Markov process  $(t_s^{t,x}, X_s^{t,x}, P)$ . We then apply F-K (2.20). The result is:

$$w(t,x) = Ef(X_t^{t,x}) \exp\{\left[\int_0^t V(t-s, X_s^{t,x})ds\right]\},$$
(2.23)

solves eqn:

$$w_t = \frac{1}{2}b^2(t, x)w_{xx} + a(t, x)w_x + V(t, x)w, \qquad (2.24)$$

w(0,x) = f(x).

All results generalize to higher space dimensions.

## **3** Weak Consistency: Definition and Examples

A discrete SDE approximation  $Y^{\delta}(t)$  is called *converging weakly* to X(t) at t = T if:

$$\lim_{\delta \to 0} |E(g(X(T))) - E(g(Y^{\delta}(T)))| = 0, \qquad (3.25)$$

for any  $g \in C$ , C a class of smooth test functions. One example of C is all polynomials, then (3.25) is same as convergence of all moments of solutions. As before, discrete times  $0 = t_0 < t_1 < t_2 < \cdots < t_n < \cdots < t_N = T$ ,  $\Delta_n = t_{n+1} - t_n$ ,  $\delta = \max \Delta_n$ . Convergence is order  $\beta > 0$  if:

$$|E(g(X(T))) - E(g(Y^{\delta}(T)))| \le C\delta^{\beta}, \qquad (3.26)$$

for small  $\delta$ .

Later we will see that Euler method is weakly convergent of order  $\beta = 1$ , while it is order 1/2 strong convergent (pathwise).

The discrete approximation is weakly consistent if

$$E\left(\left|E\left(\frac{Y_{n+1}^{\delta} - Y_{n}^{\delta}}{\Delta_{n}}|A_{t_{n}}\right) - a(t_{n}, Y_{n}^{\delta})\right|^{2}\right) \le c(\delta) \to 0,$$
(3.27)

same as in strong consistency, and:

$$E\left[\left|E\left(\frac{1}{\Delta_n}(Y_{n+1}^{\delta}-Y_n^{\delta})^2|A_n\right)-b^2(t_n,Y_n^{\delta})\right|^2\right]$$
  
$$\leq c(\delta) \to 0.$$
(3.28)

for all fixed  $Y_n^{\delta} = y, n = 0, 1, 2, \cdots$ .

For Euler, weak consistency holds. Moreover, some modified Euler like:

$$Y_{n+1} = Y_n + a(t_n, Y_n)\Delta_n + b(t_n, Y_n)\xi_n \,(\Delta_n)^{1/2},\tag{3.29}$$

where  $\xi_n$  independent two point r.v.,  $P(\xi_n = \pm 1) = 1/2$ , is weakly convergent, not strongly convergent.

## 4 Consistency implies Convergence

Consider the autonomous SDE:

$$dX_t = a(X_t)dt + b(X_t)dW_t, (4.30)$$

a, b, smooth, with polynomial growth.

**Theorem 4.1** Consider equidistant time weakly consistent discrete approximation  $Y_n^{\delta}$  of (4.30) with  $Y^{\delta}(0) = X_0$  so that:

$$E(\max_{n} |Y_{n}^{\delta}|^{2q}) \le K(1 + E(|X_{0}|^{2q})), \tag{4.31}$$

for  $q = 1, 2, \dots$ , and:

$$E(|Y_{n+1}^{\delta} - Y_n^{\delta}|^6) \le c(\delta)\Delta_n, \quad c(\delta) = o(\delta), \tag{4.32}$$

for any  $n = 0, 1, 2, \cdots$ . Then  $Y_n^{\delta}$  converges weakly to X(t).

Sketch of Proof: Write  $Y(t) = Y^{\delta}(t)$ . Use fact:

$$u(s,x) = E(g(X_T)|X_s = x), (4.33)$$

solves backward equation:

$$u_s + Lu = u_s + au_x + \frac{b^2}{2}u_{xx} = 0, (4.34)$$

and:

$$u(T,x) = g(x).$$
 (4.35)

Denote by  $X_t^{s,x}$  solution of:

$$X_t^{s,x} = x + \int_s^t a(X_r^{s,x}) dr + \int_s^t b(X_r^{s,x}) dW_r.$$
(4.36)

A key observation by Ito formula and (4.34):

$$E(u(t_{n+1}, X_{t_{n+1}}^{t_n, x}) - u(t_n, x) | A_n) = 0,$$
(4.37)

By eqns (4.33)-(4.35), write:

$$H = |E(g(Y(T))) - E(g(X(T)))|$$
  
=  $|E(u(T, Y(T)) - E(u(T, X(T)))|$   
=  $|E(u(T, Y(T)) - u(0, Y_0))|$   
=  $|E(\sum_{n=0}^{n_T-1} u(t_{n+1}, Y_{n+1}) - u(t_n, Y_n))|.$  (4.38)

By (4.37):

$$\begin{split} H &= |E(\sum [u(t_{n+1},Y_{n+1})-u(t_n,Y_n) \\ &-(u(t_{n+1},X_{t_{n+1}}^{t_n,Y_n})-u(t_n,X_{t_n}^{t_n,Y_n}))])| \\ &= |E(\sum [u(t_{n+1},Y_{n+1})-u(t_{n+1},Y_n) \\ &-(u(t_{n+1},X_{t_{n+1}}^{t_n,Y_n})-u(t_{n+1},Y_n))])| \end{split}$$

Taylor expand in x:

$$H = |E(\sum u_{x}[(Y_{n+1} - Y_{n}) - (X_{t_{n+1}}^{t_{n},Y_{n}} - Y_{n})] + \frac{1}{2}u_{xx}[(Y_{n+1} - Y_{n})^{2} - (X_{t_{n+1}}^{t_{n},Y_{n}} - Y_{n})^{2}] + O(|X_{t_{n+1}}^{t_{n},Y_{n}} - Y_{n}|^{3}) + |Y_{n+1} - Y_{n}|^{3})|$$

$$(4.39)$$

 $u_x, u_{xx}$  evaluated at  $(t_{n+1}, Y_n)$ .

Higher Moments Estimate of SDE (augmented, Theorem 4.5.4 in KL's book) Suppose that conditions in lecture 5 hold and that

 $E\left(\left|X_{t_0}\right|^{2n}\right) < \infty$ 

for some integer  $n \geq 1$ . Then the solution  $X_t$  satisfies

$$E(|X_t|^{2n}) \le (1 + E(|X_{t_0}|^{2n})) e^{C(t-t_0)}$$

and

$$E\left(|X_t - X_{t_0}|^{2n}\right) \le D\left(1 + E\left(|X_{t_0}|^{2n}\right)\right)(t - t_0)^n e^{C(t - t_0)}$$

$$H \leq C \sum E(|u_{x}| | E((Y_{n+1} - Y_{n}) - (X_{t_{n+1}}^{t_{n},Y_{n}} - Y_{n})|A_{n}) |$$

$$+ \frac{1}{2} |u_{xx}| | E(((Y_{n+1} - Y_{n})^{2} - (X_{t_{n+1}}^{t_{n},Y_{n}} - Y_{n})^{2}|A_{n})|$$

$$+ O(\delta^{3/2} + \delta^{1/2}\sqrt{c(\delta)})$$

$$\leq C \sum \delta E^{1/2} (|E(\frac{Y_{n+1} - Y_{n}}{\delta}|A_{n}) - a(t_{n},Y_{n})|^{2})$$

$$+ \delta E^{1/2} (|E(\frac{(Y_{n+1} - Y_{n})^{2}}{\delta}|A_{n}) - b^{2}(t_{n},Y_{n})|^{2})$$

$$+ O(\delta^{3/2} + \delta^{1/2}\sqrt{c(\delta)})$$

$$\leq C \sum \delta \sqrt{c(\delta)} + O(\delta^{3/2} + \delta^{1/2}\sqrt{c(\delta)})$$

$$= O(\sqrt{c(\delta)} + \delta^{1/2} + \sqrt{c(\delta)/\delta}) \rightarrow 0.$$
(4.40)