Lecture 1: Random Variables and Convergence.

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Abstract

Class notes on random variables, random number generation, distribution and convergence

1 Basic Notion and Examples

Consider throwing a die, there are 6 possible outcomes, denoted by ω_i , $i = 1, \dots, 6$; the set of all outcomes $\Omega = \{\omega_1, \dots, \omega_6\}$, is called *sample space*.

A subset of Ω , e.g. $A = \{\omega_2, \omega_4, \omega_6\}$, is called an *event*. Suppose we did N times of die experiment, event A happened N_a times, then the *probability* of event A is $P(A) = \lim_{N \to \infty} N_a/N$. For a fair die, P(A) = 1/2.

Let the collection of events be A, A a sigma-algebra of all events, meaning (1) if $E \in A$, then $E^c \in A$; (2) if $E_i \in A$, *i* countable, then $\bigcup_i E_i \in A$. The triple (Ω, A, P) is called a *probibility space*. P is a function assigning probability to events, more precisely, a probability measure satisfyng: (1) $P(E) \ge P(\Phi) = 0$, Φ null event, (2) if E_i are countably many disjoint events, $P(\bigcup_i E_i) = \sum_i P(E_i)$, (3) $P(\Omega) = 1$.

The events E and F are *independent*, if:

$$P(E \cap F) = P(E)P(F),$$

and conditional probability P(E|F) is:

$$P(E|F) = P(E \cap F)/P(F).$$

A random variable r.v. $X(\omega)$ is a function: $\Omega \to R$ such that $\{\omega \in \Omega : X(\omega) \le a\}$ is an event. The distribution function of $X(\omega)$ is:

$$F_X(x) = P(\{\omega \in \Omega : X(\omega) \le x\}), \tag{1.1}$$

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satisfying:

- (1) $\lim_{x \to -\infty} F_X(x) = 0, \lim_{x \to +\infty} F_X(x) = 1.$
- (2) $F_X(x)$ is nondecreasing, right continuous $(\{X \le y\} \to \{X \le x\} \text{ as } y \to x+0).$
- (3) $F_X(x-) = P(X < x) \ (\{X \le y\} \to \{X < x\} \text{ as } y \to x-0).$
- (4) $P(X = x) = F_X(x) F_X(x-).$

Conversely, if F satisfies (1)-(3), it's a distribution function of some r.v.

When F_X is absolutely continuous, we have a density function p(x) such that:

$$F(x) = \int_{-\infty}^{x} p(y) \, dy$$

Examples (continuous r.v): (1) Uniform distribution on [a, b]:

$$p(x) = \chi_{[a,b]}(x)/(b-a);$$

(2) unit or standard Gaussian (normal) distribution:

$$p(x) = (2\pi)^{-1/2} e^{-x^2/2};$$

(3) exponential distribution $(\lambda > 0)$:

$$p(x) = \lambda e^{-\lambda x} \chi_{(x \ge 0)};$$

Examples (discrete r.v): (1) two point r.v, taking x_1 with prob. p, x_2 with prob. 1 - p, distribution is:

$$F_X = \begin{cases} 0 & x < x_1 \\ p & x \in [x_1, x_2) \\ 1 & x \ge x_2, \end{cases}$$

(2) Poisson distribution with $(\lambda > 0)$:

$$p_n = P(X = n) = \lambda^n \exp\{-\lambda\}/n!, \ n = 0, 1, 2, \cdots.$$

Mean of a r.v. is:

$$\mu = E(X) = \sum_{j=1}^{N} x_j p_j,$$

the discrete case and:

$$\mu = E(X) = \int_{\mathbb{R}^1} x p(x) \, dx,$$

the continuous case.

Variance is: $\sigma^2 = Var(X) = E((X - \mu)^2).$

2 Random Number Generators

On digital computers, psuedo-random numbers are used as approximations of random numbers. A common algorithm is the linear recursive scheme:

$$X_{n+1} = aX_n \pmod{c},\tag{2.2}$$

a and c positive relatively prime integers, with initial value "seed" X_0 . The numbers:

$$U_n = X_n/c,$$

will be approximately uniformly distributed over [0, 1]. c is usually a large integer in powers of 2, a is a large integer relative prime to c.

Matlab command "rand(m,n)" generates $m \times n$ matrices with psuedo random entries uniformly distributed on (0,1) ($c = 2^{1492}$), using current state. S = rand('state') is a 35-element vector containing the current state of the uniform generator. rand('state',0) resets the generator to its initial state. rand('state',J), for integer J, resets the generator to its J-th state. Similarly, "randn(m,n)" generates $m \times n$ matrices with psuedo random entries standard-normally distributed, or unit Gaussian.

Example: a way to visualize the generated random numbers is:

$$t = (0: 0.01: 1)';$$

$$rand('state', 0);$$

$$y1 = rand(size(t));$$

$$randn('state', 0);$$

$$y2 = randn(size(t));$$

$$plot(t, y1, 'b', t, y2, 'g')$$

Two-point r.v. can be generated from uniformly distributed r.v. $U \in [0, 1]$ as:

$$X = \begin{cases} x_1 & U \in [0, p] \\ x_2 & U \in (p, 1] \end{cases}$$

A continuous r.v with distribution function F_X , can be generated from U as $X = F_X^{-1}(U)$ if F_X^{-1} exists, or more generally:

$$X = \inf\{x : U \le F_X(x)\}.$$

This is called inverse transform method. It applies to exponential distribution, to give:

$$X = -\ln(1-U)/\lambda, \ U \in (0,1).$$

The Box-Muller method generates Gaussian from two independent $U_i \in [0, 1], i = 1, 2$ by a nonlinear mapping:

$$N_{1} = \sqrt{-2 \ln U_{1}} \cos(2\pi U_{2}),$$

$$N_{2} = \sqrt{-2 \ln U_{1}} \sin(2\pi U_{2}),$$
(2.3)

where N_1 , N_2 are independent unit Gaussian.

A related method is Polar-Marsaglia method, mapping two independent uniformly distributed V_1, V_2 on (-1, 1) first to unit circle:

$$(V_1/\sqrt{W}, V_2/\sqrt{W}), W = V_1^2 + V_2^2,$$

then follow Box-Muller as:

$$N_{1} = V_{1}\sqrt{-2 \ln(W)/W},$$

$$N_{2} = V_{2}\sqrt{-2 \ln(W)/W}.$$
(2.4)

3 Moment Inequalities

Some useful inequalities involving moments are:

• Markov inequality:

$$P(\{\omega: X(\omega) \ge a\}) \le \frac{1}{a} E(X), \text{ if } X(\omega) \ge 0;$$

and Chebyshev inequality:

$$P(\{\omega : |X(\omega)|^2 \ge a\}) \le \frac{1}{a}E(X^2),$$

for any a > 0.

• Jensen's inequality:

$$g(E(X)) \le E(g(X)), g \text{ convex.}$$

It follows that for any 0 < r < s:

$$(E(|X-a|^r))^{1/r} \le (E(|X-a|^s))^{1/s},$$

Lyapunov inequality.

• Hölder inequality:

$$E(|X+Y|^r)^{1/r} \le E(|X|^r)^{1/r} + E(|Y|^r)^{1/r}, \ r \ge 1,$$
$$E(|X\cdot Y|) \le (E(|X|^p))^{1/p} (E(|Y|^q))^{1/q}, \ p^{-1} + q^{-1} = 1.$$

4 Joint Distribution

For n r.v's X_1, X_2, \dots, X_n , Joint Distribution Function is:

$$F_{X_1,\cdots,X_n}(x_1,\cdots,x_n) = P(\{\omega \in \Omega : X_i(\omega) \le x_i, i = 1, 2, \cdots, n\}).$$

• n=2,

$$F_{X_1,X_2} \to 0, \ x_i \to -\infty,$$

$$F_{X_1,X_2} \to 1, \ x_1, x_2 \to +\infty,$$

 F_{X_1,X_2} is nondecreasing and right continuous in x_1 and x_2 . Marginal Distribution F_{X_1} :

$$F_{X_1}(x_1) = \lim_{x_2 \to \infty} F_{X_1, X_2}(x_1, x_2)$$

Continuous r.v:

$$F_{X_1,X_2}(x_1,x_2) = \int_{-\infty}^{x_1} \int_{-\infty}^{x_2} p(y_1,y_2) dy_1 dy_2,$$

 $p \geq 0$ density.

Joint Gaussian with mean $\mu = (\mu_1, \mu_2)$ and covariance $C^{-1} = (E(X_i - \mu_i)(X_j - \mu_j)) > 0$:

$$p(x_1, x_2) = \frac{\sqrt{\det(C)}}{2\pi} \exp\{\left(-\frac{1}{2}\sum_{i,j=1}^2 c^{i,j}(x_i - \mu_i)(x_j - \mu_j)\right)\},\tag{4.5}$$

orthogonal transformation of Gaussian r.v. is Gaussian.

• Independence:

$$F_{X_1X_2}(x_1, x_2) = F_{X_1}(x_1)F_{X_2}(x_2),$$

 $p(x_1, x_2) = p_1(x_1)p_2(x_2).$

5 Convergence and Limit Theorems

Sequence of r.v. X_1, X_2, \dots, X_n :

• convergence with prob 1 (cp1):

$$P\left(\left\{\omega \in \Omega : \lim_{n \to \infty} |X_n(\omega) - X(\omega)| = 0\right\}\right) = 1;$$
(5.6)

• mean-square convergence (msc): $(E(X_i^2) \le C)$

$$\lim_{n \to \infty} E(|X_n - X|^2) = 0;$$
(5.7)

• convergence in prob (cp):

$$\lim_{n \to \infty} P(\{\omega \in \Omega : |X_n(\omega) - X(\omega)| \ge \epsilon\}) = 0, \ \forall \ \epsilon;$$
(5.8)

• convergence in law (cl):

$$\lim_{n \to \infty} F_{X_n}(x) = F_X(x), \tag{5.9}$$

at all continuous points of F_X ;

• weak convergence:

$$\lim_{n \to \infty} \int_{R^1} f(x) dF_X(x) = \int_{R^1} f(x) dF_X(x),$$
 (5.10)

for any $f \in C_0(\mathbb{R}^1)$.

- $cp1 (msc) \Longrightarrow cp \Longrightarrow cl.$
- If $|X_i| \leq |Y|$, wp1, $E(|Y|^2) < \infty$, DCT:

 $cp1 \Longrightarrow msc \Longrightarrow cp.$

Example 1: i.i.d. r.v X_i 's, with $\mu = E(X_i), \sigma^2 = Var(X_i),$

$$\frac{S_n}{n} = \frac{\sum_{i=1}^n X_i}{n} \to \mu_i$$

wp1 and msc (Strong Law of Large Numbers), cp (Weak Law of Large Numbers).

$$\frac{S_n - n\mu}{\sigma\sqrt{n}} \to N(0, 1),$$

in law, N(0, 1) unit Gaussian, Central Limit Theorem.

Example 2: Let $\Omega = [0,1]$, P([a,b]) = |b-a|, $[a,b] \subset [0,1]$. Let $A_n = \{\omega : \omega \in [0,1/n]\}, X_n = \sqrt{n}\chi_{A_n}$, then $X_n \to 0$ in probability, a.s., but not in mean-square.

6 Project I (due April 12 before lecture, 2021)

You can use any programming language, you don't need to tex your report. Please send the digital version to zhongjianwang25@gmail.com. Title will be <u>P1-(Your Name on UID)</u>.

I1. Generate $N = 10^4$ uniformly distributed pseudo random numbers on (0, 1) on Matlab (or in other environment). Partition the interval into subintervals I_j of equal length 0.05. Count the number of random numbers in I_j as N_j . Plot relative frequencies N_j/N divided by subinterval length, so called histogram. Does the histogram look like density of U(0, 1)? Compute sample average:

$$\mu_N = \frac{1}{N} \sum_{j=1}^N x_j,$$

and sample variance:

$$\sigma_N = \frac{1}{N-1} \sum_{j=1}^N (x_j - \mu_N)^2.$$

Compare them to 1/2 and 1/12, exact mean and variance of U(0, 1).

I2. Repeat I1 for unit Gaussian random numbers: partition [-2.5, 2.5] into 100 subintervals of equal length, with fixed intervals $(-\infty, -2.5)$ and $(2, 5, \infty)$ for other values.

I3. Show that the two random variables N_1, N_2 generated by Box-Muller method are Gaussian with zero mean and identity covariance when U_1, U_2 are independent U(0, 1)uniformly distributed.

I4. (1) Let $Z = (N_1, N_2)$, S an invertible 2 x 2 matrix, $\mu \in \mathbb{R}^2$, show that $X = S^T Z + \mu$ is jointly Gaussian with mean μ , and covariance matrix $S^T S$.

(2) Write a program to generate a pair of Gaussian pseudo random numbers (X_1, X_2) with zero mean and covariance $E(X_1^2) = 1$, $E(X_2^2) = 1/3$, $E(X_1X_2) = 1/2$. Generate 1000 pairs of such numbers, evaluate their sample averages and sample covariances.