

# Lecture 6: Euler Approximation

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## Abstract

Backward and forward representation, strong and weak convergence of Euler approximation.

## 1 Euler Method: Order of Convergence

SDE:

$$dX_t = a(t, X_t)dt + b(t, X_t)dW_t, \quad t \in (0, T], \quad (1.1)$$

with initial value  $X_0$  at  $t = 0$ . Discrete times  $0 = t_0 < t_1 < t_2 < \dots < t_n < \dots < t_N = T$ . Denote  $\Delta_n = t_{n+1} - t_n$ ,  $\delta = \max \Delta_n$ .

Euler approximation:

$$Y_{n+1} = Y_n + a(t_n, Y_n)\Delta_n + b(t_n, Y_n)(W_{t_{n+1}} - W_{t_n}), \quad (1.2)$$

with  $Y_0 = X_0$ .

$Y_n$  is  $A_n$  measurable.

Connecting the adjacent discrete values  $Y_n$  by straight lines form a continuous function  $Y(t)$ . Pathwise measure of approximation is:

$$\epsilon = E(|X(T) - Y(T)|), \quad (1.3)$$

reduces to deterministic absolute error at  $t = T$  if noise is absent. In actual computation, suppose we have  $N$  solutions  $Y_k(T)$  from  $N$  realizations of BM, then  $\epsilon$  is approximated by:

$$\tilde{\epsilon} = \frac{1}{N} \sum_{k=1}^N |X_k(T) - Y_k(T)|. \quad (1.4)$$

It is an amusing fact that  $\epsilon \sim O(\delta^{1/2})$  in the stochastic case while  $\epsilon \sim O(\delta)$  in the deterministic case. This is analyzed below.

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## 1.1 Strong Convergence/Consistency

*Strong Convergence if:*

$$\lim_{\delta \rightarrow 0} E(|X(T) - Y_\delta(T)|) = 0. \quad (1.5)$$

*Strong Convergence with order  $\gamma > 0$ :*

$$E(|X(T) - Y_\delta(T)|) \leq C\delta^\gamma, \quad (1.6)$$

for any  $\delta \in [0, \delta_0]$ ,  $\delta_0 > 0$ .

*Strong Consistency of Discrete Approximation:*

$$E \left( \left| E \left( \frac{Y_{n+1}^\delta - Y_n^\delta}{\Delta_n} \middle| A_{t_n} \right) - a(t_n, Y_n^\delta) \right|^2 \right) \leq c(\delta) \rightarrow 0, \quad (1.7)$$

and:

$$\begin{aligned} & E \left[ \frac{1}{\Delta_n} |Y_{n+1}^\delta - Y_n^\delta - E(Y_{n+1}^\delta - Y_n^\delta | A_{t_n}) - b(t_n, Y_n^\delta) \Delta W_n|^2 \right] \\ & \leq c(\delta) \rightarrow 0. \end{aligned} \quad (1.8)$$

for all fixed  $Y_n^\delta = y$ ,  $n = 0, 1, 2, \dots$ .

For Euler, strong consistency holds with  $c(\delta) \equiv 0$ .

## 1.2 Convergence

Consider the autonomous SDE:

$$dX_t = a(X_t)dt + b(X_t)dW_t, \quad (1.9)$$

**Theorem 1.1** *A strongly consistent equidistant time discrete approximation  $Y_n^\delta$  of (1.9) with  $Y^\delta(0) = X_0$  converges strongly to  $X$ . In particular, Euler method converges strongly with order 1/2.*

*Sketch of Proof:*

$$Z(t) = \sup_{s \in [0, t]} E(|Y_{n_s}^\delta - X(s)|^2),$$

$$n_s = \max\{n : t_n \leq s\}.$$

$$Z(t) = \sup_{s \in [0, t]} E \left[ \left| \sum_{n=0}^{n_s-1} (Y_{n+1}^\delta - Y_n^\delta) - \int_0^s a(X_r)ds - \int_0^s b(X_r)dW_r \right|^2 \right]$$

$$\begin{aligned}
&\leq C_1 \sup_{s \in [0, t]} \left\{ E \left[ \left| \sum_{n=0}^{n_s-1} (E(Y_{n+1}^\delta - Y_n^\delta | A_{t_n}) - a(Y_n^\delta) \Delta_n) \right|^2 \right] \right. \\
&+ E \left[ \left| \sum_{n=0}^{n_s-1} (Y_{n+1}^\delta - Y_n^\delta - E(Y_{n+1}^\delta - Y_n^\delta | A_{t_n}) - b(Y_n^\delta) \Delta W_n) \right|^2 \right] \\
&+ E \left[ \left| \int_0^{t_{n_s}} a(Y_{n_r}^\delta) - a(X_r) dr \right|^2 \right] + E \left[ \left| \int_0^{t_{n_s}} b(Y_{n_r}^\delta) - b(X_r) dW_r \right|^2 \right] \\
&+ \left. E \left[ \left| \int_{t_{n_s}}^s a(X_s) ds \right|^2 \right] + E \left[ \left| \int_{t_{n_s}}^s b(X_s) dW_s \right|^2 \right] \right\} \tag{1.10}
\end{aligned}$$

by strong consistency and Lipschitz condition:

$$Z(t) \leq C_2 \int_0^t Z(s) ds + C_3(\delta + c(\delta)), \tag{1.11}$$

the last term of (1.10) contributes  $O(\delta)$ .

Gronwall inequality:

$$Z(t) \leq C_4(\delta + c(\delta)), \tag{1.12}$$

or:

$$E(|Y^\delta(T) - X(T)|) \leq C_5 \sqrt{\delta + c(\delta)}, \tag{1.13}$$

strong convergence. For Euler,  $c(\delta) = 0$ ,  $\gamma = 1/2$ .

## 2 Backward and Forward Representations

Let  $X(t)$  be a diffusion process (solution of SDE) with drift  $a(t, x)$ , diffusion  $b(t, x)$ :

$$dX_t = a dt + b dW_t,$$

consider the conditional expectation ( $s < t$ ):

$$E(f(X_t) | X_s = x) = \int f(y) p(s, x; t, y) dy, \tag{2.14}$$

where  $p(s, x; t, y)$  is the transition probability density function from  $(s, x)$  to  $(t, y)$ . As a function of  $(s, x)$ ,  $p$  satisfies the *backward equation*:

$$p_s + \frac{1}{2} b^2(s, x) p_{xx} + a(s, x) p_x = 0. \tag{2.15}$$

Hence  $u(s, x) = E(f(X_t) | X_s = x)$  solves (2.15) with final condition  $u(t, x) = f(x)$ .

**For the forward representation**, consider the *Autonomous case*,  $a = a(x)$ ,  $b = b(x)$ .

Then  $p(s, t; x, y) = p(t - s; x, y)$ ,  $p_s = -p_t$ ,

$$p_t = \frac{1}{2} b^2(x) p_{xx} + a(x) p_x, \quad t > s, \tag{2.16}$$

$p(t; x, y) \rightarrow \delta(y - x)$ , as  $t \rightarrow 0+$ . The transition probability density becomes fundamental solution of parabolic equation (2.16). As a function of  $(t, x)$ ,

$$v(t, x) = E(f(X_t)|X_s = x) = \int f(y) p(t - s; x, y) dy, \quad (2.17)$$

solves:

$$v_t = \frac{1}{2}b^2(x)v_{xx} + a(x)v_x, \quad (2.18)$$

with initial data  $v(s, x) = f(x)$ .

**Feynman-Kac Formula** Eq. (2.17) is a probabilistic representation formula of PDE (2.18). It can be generalized to include a lower order (potential,  $V$ ) term as in Eqn:

$$w_t = \frac{1}{2}b^2(x)w_{xx} + a(x)w_x + V(x)w, \quad t > 0, \quad (2.19)$$

initial data:  $w(0, x) = f(x)$ . Then,

$$w(t, x) = E \left[ \exp \left\{ \int_0^t V(X(\tau)) d\tau \right\} f(X(t)) \right], \quad (2.20)$$

Rmk: If the diffusion  $b(x) \equiv 0$ , F-K formula reduces to a solution formula of first order hyperbolic eqn by the method of characteristics.

**To derive (2.20)**, let:

$$T_t f = E \left[ \exp \left\{ \int_0^t V(X(\tau)) d\tau \right\} f(X(t)) \right],$$

a linear bounded (non-negative) operator on the space of bounded continuous functions.

Note:

$$\exp \left\{ \int_0^t V(X_s) ds \right\} = 1 + \int_0^t V(X_s) ds + o(t),$$

as  $t \rightarrow 0+$ . We have for any  $f(x)$  in the domain of  $T_t$ :

$$\begin{aligned} \frac{T_t f(x) - f(x)}{t} &= \frac{1}{t} \left( E[f(X_t) e^{\int_0^t V(X_s) ds}] - f(x) \right) \\ &= \frac{1}{t} (E[f(X_t)] - f(x)) + \frac{1}{t} E[f(X_t) \int_0^t V(X_s) ds] \\ &\rightarrow (b^2(x)f_{xx}/2 + a(x)f_x) + V(x)f. \end{aligned} \quad (2.21)$$

We have used (2.16) for the limit of first term.

**To generalize F-K to nonautonomous case**, we should notice trick in (2.16) no longer works. Treat  $t$  as a parameter,

$$\begin{aligned} dX_s^{t,x} &= a(t_s^{t,x}, X_s^{t,x}) ds + b(t_s^{t,x}, X_s^{t,x}) dW_s, \\ dt_s^{t,x} &= -ds, \end{aligned} \quad (2.22)$$

$X_0^{t,x} = x$ ,  $t_0^{t,x} = t$ , symmetrically extending  $a$ ,  $b$ :  $a(-\tau, x) = a(\tau, x)$  etc. View (2.22) as a diffusion process on  $(t, x) \in \mathbb{R}^2$  with time  $s$ . Eqs (2.22) are autonomous, and define a Markov process  $(t_s^{t,x}, X_s^{t,x}, P)$ . We then apply F-K (2.20). The result is:

$$w(t, x) = Ef(X_t^{t,x}) \exp\left\{\left[\int_0^t V(t-s, X_s^{t,x}) ds\right]\right\}, \quad (2.23)$$

solves eqn:

$$w_t = \frac{1}{2}b^2(t, x)w_{xx} + a(t, x)w_x + V(t, x)w, \quad (2.24)$$

$$w(0, x) = f(x).$$

All results generalize to higher space dimensions.

### 3 Weak Consistency: Definition and Examples

A discrete SDE approximation  $Y^\delta(t)$  is called *converging weakly* to  $X(t)$  at  $t = T$  if:

$$\lim_{\delta \rightarrow 0} |E(g(X(T))) - E(g(Y^\delta(T)))| = 0, \quad (3.25)$$

for any  $g \in \mathcal{C}$ ,  $\mathcal{C}$  a class of smooth test functions. One example of  $\mathcal{C}$  is all polynomials, then (3.25) is same as convergence of all moments of solutions. As before, discrete times  $0 = t_0 < t_1 < t_2 < \dots < t_n < \dots < t_N = T$ ,  $\Delta_n = t_{n+1} - t_n$ ,  $\delta = \max \Delta_n$ . Convergence is order  $\beta > 0$  if:

$$|E(g(X(T))) - E(g(Y^\delta(T)))| \leq C\delta^\beta, \quad (3.26)$$

for small  $\delta$ .

Later we will see that Euler method is weakly convergent of order  $\beta = 1$ , while it is order 1/2 strong convergent (pathwise).

The discrete approximation is *weakly consistent* if

$$E\left(\left|E\left(\frac{Y_{n+1}^\delta - Y_n^\delta}{\Delta_n} \middle| A_{t_n}\right) - a(t_n, Y_n^\delta)\right|^2\right) \leq c(\delta) \rightarrow 0, \quad (3.27)$$

same as in strong consistency, and:

$$\begin{aligned} & E\left[\left|E\left(\frac{1}{\Delta_n}(Y_{n+1}^\delta - Y_n^\delta)^2 \middle| A_n\right) - b^2(t_n, Y_n^\delta)\right|^2\right] \\ & \leq c(\delta) \rightarrow 0. \end{aligned} \quad (3.28)$$

for all fixed  $Y_n^\delta = y$ ,  $n = 0, 1, 2, \dots$ .

For Euler, weak consistency holds. Moreover, some modified Euler like:

$$Y_{n+1} = Y_n + a(t_n, Y_n)\Delta_n + b(t_n, Y_n)\xi_n (\Delta_n)^{1/2}, \quad (3.29)$$

where  $\xi_n$  independent two point r.v.,  $P(\xi_n = \pm 1) = 1/2$ , is weakly convergent, not strongly convergent.

## 4 Consistency implies Convergence

Consider the autonomous SDE:

$$dX_t = a(X_t)dt + b(X_t)dW_t, \quad (4.30)$$

$a, b$ , smooth, with polynomial growth.

**Theorem 4.1** Consider equidistant time weakly consistent discrete approximation  $Y_n^\delta$  of (4.30) with  $Y^\delta(0) = X_0$  so that:

$$E(\max_n |Y_n^\delta|^{2q}) \leq K(1 + E(|X_0|^{2q})), \quad (4.31)$$

for  $q = 1, 2, \dots$ , and:

$$E(|Y_{n+1}^\delta - Y_n^\delta|^6) \leq c(\delta)\Delta_n, \quad c(\delta) = o(\delta), \quad (4.32)$$

for any  $n = 0, 1, 2, \dots$ . Then  $Y_n^\delta$  converges weakly to  $X(t)$ .

*Sketch of Proof:* Write  $Y(t) = Y^\delta(t)$ .

Use fact:

$$u(s, x) = E(g(X_T)|X_s = x), \quad (4.33)$$

solves backward equation:

$$u_s + Lu = u_s + au_x + \frac{b^2}{2}u_{xx} = 0, \quad (4.34)$$

and:

$$u(T, x) = g(x). \quad (4.35)$$

Denote by  $X_t^{s,x}$  solution of:

$$X_t^{s,x} = x + \int_s^t a(X_r^{s,x})dr + \int_s^t b(X_r^{s,x})dW_r. \quad (4.36)$$

A key observation by Ito formula and (4.34) :

$$E(u(t_{n+1}, X_{t_{n+1}}^{t_n, x}) - u(t_n, x)|A_n) = 0, \quad (4.37)$$

By eqns (4.33)-(4.35), write:

$$\begin{aligned} H &= |E(g(Y(T))) - E(g(X(T)))| \\ &= |E(u(T, Y(T))) - E(u(T, X(T)))| \\ &= |E(u(T, Y(T))) - u(0, Y_0)| \\ &= |E(\sum_{n=0}^{n_T-1} u(t_{n+1}, Y_{n+1}) - u(t_n, Y_n))|. \end{aligned} \quad (4.38)$$

By (4.37):

$$\begin{aligned}
H &= |E(\sum [u(t_{n+1}, Y_{n+1}) - u(t_n, Y_n) \\
&\quad - (u(t_{n+1}, X_{t_{n+1}}^{t_n, Y_n}) - u(t_n, X_{t_n}^{t_n, Y_n}))])| \\
&= |E(\sum [u(t_{n+1}, Y_{n+1}) - u(t_{n+1}, Y_n) \\
&\quad - (u(t_{n+1}, X_{t_{n+1}}^{t_n, Y_n}) - u(t_{n+1}, Y_n))])|
\end{aligned}$$

Taylor expand in  $x$ :

$$\begin{aligned}
H &= |E(\sum u_x [(Y_{n+1} - Y_n) - (X_{t_{n+1}}^{t_n, Y_n} - Y_n)] \\
&\quad + \frac{1}{2} u_{xx} [(Y_{n+1} - Y_n)^2 - (X_{t_{n+1}}^{t_n, Y_n} - Y_n)^2] \\
&\quad + O(|X_{t_{n+1}}^{t_n, Y_n} - Y_n|^3) + |Y_{n+1} - Y_n|^3)| \tag{4.39}
\end{aligned}$$

$u_x, u_{xx}$  evaluated at  $(t_{n+1}, Y_n)$ .

Higher Moments Estimate of SDE (augmented, Theorem 4.5.4 in KL's book)  
Suppose that conditions in lecture 5 hold and that

$$E(|X_{t_0}|^{2n}) < \infty$$

for some integer  $n \geq 1$ . Then the solution  $X_t$  satisfies

$$E(|X_t|^{2n}) \leq (1 + E(|X_{t_0}|^{2n})) e^{C(t-t_0)}$$

and

$$E(|X_t - X_{t_0}|^{2n}) \leq D (1 + E(|X_{t_0}|^{2n})) (t - t_0)^n e^{C(t-t_0)}$$

$$\begin{aligned}
H &\leq C \sum E(|u_x| |E((Y_{n+1} - Y_n) - (X_{t_{n+1}}^{t_n, Y_n} - Y_n) | A_n)| \\
&\quad + \frac{1}{2} |u_{xx}| |E((Y_{n+1} - Y_n)^2 - (X_{t_{n+1}}^{t_n, Y_n} - Y_n)^2 | A_n)| \\
&\quad + O(\delta^{3/2} + \delta^{1/2} \sqrt{c(\delta)}) \\
&\leq C \sum \delta E^{1/2} (|E(\frac{Y_{n+1} - Y_n}{\delta} | A_n) - a(t_n, Y_n)|^2) \\
&\quad + \delta E^{1/2} (|E(\frac{(Y_{n+1} - Y_n)^2}{\delta} | A_n) - b^2(t_n, Y_n)|^2) \\
&\quad + O(\delta^{3/2} + \delta^{1/2} \sqrt{c(\delta)}) \\
&\leq C \sum \delta \sqrt{c(\delta)} + O(\delta^{3/2} + \delta^{1/2} \sqrt{c(\delta)}) \\
&= O(\sqrt{c(\delta)} + \delta^{1/2} + \sqrt{c(\delta)/\delta}) \rightarrow 0. \tag{4.40}
\end{aligned}$$