

# Lecture 5: Strong and Weak Solution

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## Abstract

Strong and Weak Solution of SDE

## 1 Integral Formulation of SDE

Recall definition of SDE:

$$dX_t = a(t, X_t)dt + b(t, X_t)dW_t, \quad (1.1)$$

and the corresponding SIE:

$$X_t = X_0 + \int_0^t a(s, X_s)ds + \int_0^t b(s, X_s)dW_s. \quad (1.2)$$

**Strong solution** is defined for each BM  $W_t$  and its filtration  $A_t$ , each initial data  $X_0$ , there is a process  $X_t$ ,  $t \geq 0$ , with continuous sample path such that  $X_t$  is adapted to  $A_t$ , and a solution of SIE (1.2).

**Uniqueness of strong solution:** for given initial data  $X_0$ , there is only one solution to SIE (1.2)

- in the mean square sense  $E \int_0^T |X_t - \tilde{X}_t|^2 dt = 0$ ;
- in the pathwise sense:  $P(\sup_{t \in [0, T]} |X_t - \tilde{X}_t| > 0) = 0$ .

**Eg.** Recall in last lecture when we define vector SDE, we need vector BM  $W_t$  whose entries  $W^1, W^2$ .  $W^1, W^2$  share same joint distribution but they are not identical in MS sense or pathwise sense.

### 1.1 Sufficient Conditions

Throughout this course, we are expecting only to solve SDE with unique solution. Here we list three usually assumes condition that sufficiently provides existence and uniqueness.

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(A1) Lipschitz:  $a, b$  are measurable in  $(t, x)$ , Lipschitz in  $x$ :

$$\begin{aligned} |a(t, x) - a(t, y)| &\leq K|x - y|, \\ |b(t, x) - b(t, y)| &\leq K|x - y|, \end{aligned} \tag{1.3}$$

for any  $t \in [0, T]$ ,  $x, y$ .

(A2) Linear growth bound:

$$|a(t, x)|^2 \leq K^2(1 + |x|^2), \quad |b(t, x)|^2 \leq K^2(1 + |x|^2), \tag{1.4}$$

for any  $t \in [0, T]$ ,  $x, y$ .

(A3)  $X_0$  is  $A_0$  measurable,  $E(|X_0|^2) < \infty$ .

## 1.2 Gronwall Inequality

**Differential Form:** Given interval  $I = [a, b]$  on real line, if

$$u'(t) \leq \beta(t)u(t), \quad t \in I^\circ$$

then  $u$  is bounded by :

$$u(t) \leq u(a) \exp \left( \int_a^t \beta(s) ds \right)$$

for all  $t \in I$ .

**Integral Form (only works for deterministic integral):** If  $u(t)$  satisfies:

- (a) If  $\beta$  is non-negative and if  $u$  satisfies the integral inequality

$$u(t) \leq \alpha(t) + \int_a^t \beta(s)u(s)ds, \quad \forall t \in I,$$

then

$$u(t) \leq \alpha(t) + \int_a^t \alpha(s)\beta(s) \exp \left( \int_s^t \beta(r)dr \right) ds, \quad t \in I.$$

- (b) If, in addition, the function  $\alpha$  is non-decreasing, then

$$u(t) \leq \alpha(t) \exp \left( \int_a^t \beta(s)ds \right), \quad t \in I.$$

-(c) If, in addition,  $\alpha, \beta$  are constant, then

$$u(t) \leq \alpha \exp \left( \beta(t - a) \right)$$

### 1.3 Uniqueness

Suppose  $X_t, Y_t$  are two solutions of SIE with same initial data ( $X_0 = Y_0$ ),  $Z_t = X_t - Y_t$ :

$$\begin{aligned} Z_t &= \int_0^t (a(s, X_s) - a(s, Y_s)) ds \\ &\quad + \int_0^t (b(s, X_s) - b(s, Y_s)) dW_s. \end{aligned} \tag{1.5}$$

By Cauchy-Schwarz, mean square property of Ito integral, (A1):

$$\begin{aligned} E(|Z_t|^2) &\leq 2E\left[\left|\int_0^t (a(s, X_s) - a(s, Y_s)) ds\right|^2\right] \\ &\quad + 2E\left[\left|\int_0^t (b(s, X_s) - b(s, Y_s)) dW_s\right|^2\right] \\ &\leq 2T \int_0^t E[|a(s, X_s) - a(s, Y_s)|^2] ds \\ &\quad + 2 \int_0^t E[|b(s, X_s) - b(s, Y_s)|^2] ds \\ &\leq L \int_0^t E[|Z_s|^2] ds, \end{aligned} \tag{1.6}$$

$L = 2(T + 1)K^2$ . Gronwall implies  $E(|Z_t|^2) = 0$ , uniqueness in the mean square sense. With more work, one can show that pathwise uniqueness also holds.

#### 1.3.1 If $E|X_0|^2$ is unbounded

Let  $X_t$  and  $\tilde{X}_t$  be two such solutions of SIE on  $[0, T]$  with, almost surely, continuous sample paths. **Since they may not have finite second moments**, we shall use the following truncation procedure: for  $N > 0$  and  $t \in [0, T]$  we define

$$I_t^{(N)}(\omega) = \begin{cases} 1 & : |X_u(\omega)|, |\tilde{X}_u(\omega)| \leq N \text{ for } 0 \leq u \leq t \\ 0 & : \text{otherwise} \end{cases}$$

Obviously  $I_t^{(N)}$  is  $\mathcal{A}_t$ -measurable and  $I_t^{(N)} = I_t^{(N)} I_s^{(N)}$  for  $0 \leq s \leq t$ . Consequently the integrals in the following expression are meaningful:

$$\begin{aligned} Z_t^{(N)} &= I_t^{(N)} \int_0^t I_s^{(N)} \left( a(s, X_s) - a(s, \tilde{X}_s) \right) ds \\ &\quad + I_t^{(N)} \int_0^t I_s^{(N)} \left( b(s, X_s) - b(s, \tilde{X}_s) \right) dW_s \end{aligned} \tag{1.7}$$

where  $Z_t^{(N)} = I_t^{(N)} (X_t - \tilde{X}_t)$ . From the Lipschitz condition we then have

$$\begin{aligned} \max \left\{ \left| I_s^{(N)} \left( a(s, X_s) - a(s, \tilde{X}_s) \right) \right|, \left| I_s^{(N)} \left( b(s, X_s) - b(s, \tilde{X}_s) \right) \right| \right\} \\ \leq K I_s^{(N)} |X_s - \tilde{X}_s| \leq 2KN \end{aligned} \quad (1.8)$$

for  $0 \leq s \leq t$ . Thus the second order moments exist for  $Z_t^{(N)}$  and the two integrals in (1.7). Using the inequality  $(a+b)^2 \leq 2(a^2+b^2)$ , the Cauchy-Schwarz inequality, we obtain from

$$\begin{aligned} E \left( \left| Z_t^{(N)} \right|^2 \right) &\leq 2E \left( \left| \int_0^t I_s^{(N)} \left( a(s, X_s) - a(s, \tilde{X}_s) \right) ds \right|^2 \right) \\ &\quad + 2E \left( \left| \int_0^t I_s^{(N)} \left( b(s, X_s) - b(s, \tilde{X}_s) \right) dW_s \right|^2 \right) \\ &\leq 2T \int_{t_0}^t E \left( \left| I_s^{(N)} \left( a(s, X_s) - a(s, \tilde{X}_s) \right) \right|^2 \right) ds \\ &\quad + 2 \int_0^t E \left( \left| I_s^{(N)} \left( b(s, X_s) - b(s, \tilde{X}_s) \right) \right|^2 \right) ds \end{aligned}$$

which we combine with (1.8) to get

$$E \left( \left| Z_t^{(N)} \right|^2 \right) \leq L \int_0^t E \left( \left| Z_s^{(N)} \right|^2 \right) ds$$

for  $t \in [0, T]$  where  $L = 2(T+1)K^2$ . We then apply the Gronwall inequality to conclude that

$$E \left( \left| Z_t^{(N)} \right|^2 \right) = E \left( \left| I_t^{(N)} \left( X_t - \tilde{X}_t \right) \right|^2 \right) = 0$$

and hence that  $I_t^{(N)} X_t = I_t^{(N)} \tilde{X}_t$ , w.p.1, for each  $t \in [0, T]$ . Note,

$$P \left( I_t^{(N)} \neq 1 \forall t \in [0, T] \right) \leq P \left( \sup_{0 \leq t \leq T} |X_t| > N \right) + P \left( \sup_{0 \leq t \leq T} |\tilde{X}_t| > N \right).$$

Since the sample paths are continuous almost surely they are bounded almost surely, we can make the probability on the right arbitrarily small by taking  $N$  sufficiently large. This means that  $P \left( X_t \neq \tilde{X}_t \right) = 0$  for each  $t \in [0, T]$ .

And then  $P \left( X_t \neq \tilde{X}_t : t \in D \right) = 0$  for any **countably** dense subset  $D$  of  $[0, T]$ . As the solutions are continuous and coincide on a countably dense subset of  $[0, T]$ , they must coincide, almost surely, on the entire interval  $[0, T]$ .

## 1.4 Existence

Picard iteration:

$$X_t^{n+1} = X_0 + \int_0^t a(s, X_s^n) ds + \int_0^t b(s, X_s^n) dW_s, \quad (1.9)$$

$X_t^n$  all measurable in  $A_t$ ,  $X_t^0 = X_0$ . Second moment estimate:

$$\begin{aligned} E[|X_t^{n+1}|^2] &\leq 3E[|X_0|^2] + 3E\left[\left|\int_0^t a(s, X_s^n) ds\right|^2\right] \\ &\quad + 3E\left[\left|\int_0^t b(s, W_s) dW_s\right|^2\right] \\ &\leq 3E[|X_0|^2] + 3TE\left[\int_0^t |a(s, X_s^n)|^2 ds\right] \\ &\quad + 3E\left[\int_0^t |b(s, X_s^n)|^2 ds\right] \\ &\leq 3E[|X_0|^2] + 3(T+1)K^2E\left[\int_0^t 1 + |X_s^n|^2\right] \end{aligned} \quad (1.10)$$

implying  $\sup_{t \in [0, T]} E[|X_t^n|^2] \leq C_0 < \infty$ , for all  $n$ . (by induction)

As in uniqueness:

$$E(|X_t^{n+1} - X_t^n|^2) \leq L \int_0^t E(|X_s^n - X_s^{n-1}|^2) ds \quad (1.11)$$

iterating:

$$E(|X_t^{n+1} - X_t^n|^2) \leq \frac{L^n}{(n-1)!} \int_0^t (t-s)^{n-1} E[|X_s^1 - X_s^0|^2] ds. \quad (1.12)$$

By growth bound (A2):

$$E[|X_t^1 - X_t^0|^2] \leq L \int_0^t (1 + E[|X_s^0|^2]) \leq C_1 < \infty, \quad (1.13)$$

then (1.12):

$$E(|X_t^{n+1} - X_t^n|^2) \leq C_1 L^n t^n / n!,$$

or:

$$\sup_{t \in [0, T]} E(|X_t^{n+1} - X_t^n|^2) \leq C_1 L^n T^n / n!,$$

implying  $X_t^n$  converges in mean square sense for  $t \in [0, T]$ .

Note:  $\mathcal{L}_T^2$  equipped with,

$$\|f\|_{2, T} = \sqrt{\int_0^T E(f(t, \cdot)^2) dt} \quad (1.14)$$

is a Banach space space.

The limit is a solution of SIE (some work needed to achieve path-wise convergence and then pass the limit, see KL's book p133).

**Prior estimate** If  $E[|X_0|^{2n}] < \infty$ ,

$$E[|X_t|^{2n}] \leq (1 + E[|X_0|^{2n}])e^{Ct}. \quad (1.15)$$

**Eg of Non existence** Consider SDE we discuss last lecture:

$$dY_t = -\frac{1}{2}e^{-2Y_t}dt + e^{-Y_t}dW_t, \quad (1.16)$$

has unique solution:

$$Y_t = \ln(W_t + e^{Y_0}),$$

valid until time:

$$T = T(Y_0(\omega)) = \min\{t \geq 0 : W_t(\omega) + e^{Y_0(\omega)} = 0.\}$$

Growth condition (A2) is not satisfied.

## 1.5 Generalized results

### 1.5.1 Lipschitz Condition

Lipschitz condition in  $b$  can be replaced by Yamada condition:

$$|b(t, x) - b(t, y)| \leq \rho(|x - y|), \quad \rho(0) = 0, \quad \int_{0^+} \rho^{-2}(u)du = +\infty. \quad (1.17)$$

One can take  $\rho(u) = u^q$ ,  $q \in [1/2, 1]$ .

*Example:*

SDE  $dX_t = |X_t|^q dW_t$ ,  $X_0 = 0$ , has unique solution if  $q \in [1/2, 1]$ .

But SDE:

$$dX_t = \frac{1}{3}X_t^{1/3}dt + X_t^{2/3}dW_t, \quad (1.18)$$

with initial data  $X_0 = 0$  has nontrivial solution (hence nonuniqueness):

$$X_t = (W_t/3)^3.$$

### 1.5.2 Growth Condition

Growth condition on drift coefficient  $a$  can be replaced by:

$$xa(t, x) \leq K(1 + |x|^2),$$

allowing  $a = x - x^3$ .

The idea comes from

$$\frac{1}{2} \frac{d}{dt} x^2 = xa(x) = x^2 - x^4 \leq x^2$$

## 1.6 Stability

If as  $\epsilon \rightarrow 0$ :

$$E[|X_0^\epsilon - X_0|^2] \rightarrow 0,$$

$$\sup_{|x| \leq N} |a^\epsilon(t, x) - a(t, x)| \rightarrow 0, \quad t \in [0, T], \quad \forall N,$$

$$\sup_{|x| \leq N} |b^\epsilon(t, x) - b(t, x)| \rightarrow 0, \quad t \in [0, T], \quad \forall N,$$

then (by Gronwall Inequality):

$$\sup_{t \in [0, T]} E[|X_t^\epsilon - X_t|^2] \rightarrow 0.$$

*Example:* Solutions of SDE:

$$dX_t^\epsilon = a(t, X_t^\epsilon)dt + \epsilon dW_t, \quad (1.19)$$

converge in the mean square sense to those of deterministic ODE:  $X_t' = a(t, X_t)$  with same initial data.

## 2 Diffusion Process and Weak Solution

### 2.1 Strong Solution as a diffusion process

Recall definition of Diffusion process,

Markov process with transition density is called *diffusion process* if the following limits exist:

Jump:

$$\lim_{t \rightarrow s^+} \frac{1}{t - s} \int_{|y-x| > \epsilon} p(s, x; t, y) dy = 0,$$

Drift:

$$\lim_{t \rightarrow s^+} \frac{1}{t - s} \int_{|y-x| \leq \epsilon} (y - x) p(s, x; t, y) dy = a(s, x),$$

Diffusion:

$$\lim_{t \rightarrow s^+} \frac{1}{t - s} \int_{|y-x| \leq \epsilon} (y - x)^2 p(s, x; t, y) dy = b^2(s, x).$$

*Theorem* Assume that  $a$  and  $b$  are continuous and that A1-A3 hold. Then the solution  $X_t$  of (1.1) for any fixed initial value  $X_{t_0}$  is a diffusion process on  $[t_0, T]$  with drift  $a(t, x)$  and diffusion coefficient  $b(t, x)$ .

## 2.2 Diffusion process as a Weak Solution

Note as we turn investigate strong solution as a diffusion process, we only verify the transition density of the distribution.

Given a diffusion process,  $Y$ , on  $[0, T]$  with drift  $a(t, y)$  and strictly positive diffusion coefficient  $b(t, y)$ . Under some assumptions (see Theorem 4.7.1 in K-L's book), we can show  $Y_t$  satisfies some SDE driven by BM.

**To show this**, we define functions  $g$  and  $\bar{a}$  by

$$g(t, y) = \int_0^y \frac{dx}{b(t, x)} \quad (2.20)$$

and

$$\bar{a}(t, z) = \left( \frac{\partial g}{\partial t} + a \frac{\partial g}{\partial y} + \frac{1}{2} b^2 \frac{\partial^2 g}{\partial y^2} \right) (t, g^{-1}(t, z)) \quad (2.21)$$

with  $a$  and  $b$  evaluated at  $(t, y)$ , where  $y = g^{-1}(t, z)$  is the inverse of  $z = g(t, y)$ . Then we define a process  $Z_t = g(t, Y_t)$ , which is a diffusion process with drift  $\bar{a}(t, z)$  and diffusion coefficient 1.

And the process

$$\tilde{W}_t = Z_t - Z_0 - \int_0^t \bar{a}(s, Z_s) ds \quad (2.22)$$

which will turn out to be a Wiener process. (Some proof needed here.)

Consequently (2.22) will be equivalent to the stochastic differential equation

$$dZ_t = \bar{a}(t, Z_t) dt + 1d\tilde{W}_t$$

which, by (2.20),(2.21) and Ito's formula, will imply that  $Y_t$  is a solution of the stochastic differential equation

$$dY_t = a(t, Y_t) dt + b(t, Y_t) d\tilde{W}_t.$$

### Example to discuss

1. In vector SDE

$$dX_t = I_2 dW_t$$

$X^1, X^2$  are not identical in path but share same distribution.

- 2.

$$dX_t = \text{sgn } X_t dt + dW_t$$

where  $\text{sgn } x = +1$  if  $x \geq 0$  and  $-1$  if  $x < 0$ , only has weak solutions, but no strong solution for the initial value  $X_0 = 0$ . In fact, if  $X_t$  is such a weak solution for the Wiener process  $W$ , then  $-X_t$  is a weak solution for the Wiener process  $-W$ . These solutions have the same probability law, but not the same sample paths.